

# Description Siemens S7-1500 function block OVP81x-ProtV2

Version 1.0

Obstacle Detection System (ODS) and Pick and Drop System (PDS) with device interface protocol-version V2.x via TCP



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# Contents

1.	Pret	face	2
	I.	Disclaimer	2
	II.	Demo Software and Templates	2
	III.	Customer-specific software	2
2.	Req	uirements	3
3.	Fun	ction Block Description	4
4.	Inte	gration of the Function Block into the User Program1	2
	4.1.	Inserting the Function Block into the User Program1	2
	4.2.	Setting the Connection Parameters 1	2
	4.3.	Calling the Instances of the Function Block in the User Program1	3
5.	Con	trol of the ODS and PDS Applications of the VPU with the help of the Function Block OVP81x-ProtV2	4
	5.1.	Connect to the VPU	4
	5.2.	ODS Application Commands1	4
	5.3.	PDS Application Commands1	5
6.	Арр	pendix 1	7
	6.1.	Display in the Output Parameter ComStatus 1	7
	6.2.	Display in the Command Error Info Outputs in ODS_Result and PDS_Result Structures	8
	6.3.	Setting the IP Address of the CPU in the TIA Portal 1	8
	6.4.	Displaying the Hardware ID of the CPU Ethernet Interface in the TIA Portal	8



Preface

# 1. Preface

In the user program of an S7 1500 controller, the function block *OVP81x-ProtV2* is intended to simplify data exchange via the TCP interface with the PLC server application of a Video Processing Unit (VPU) series OVP81x from ifm electronic gmbh. The block was created in SCL by means of the TIA Portal software V16 in the editing language English (USA).

This document

- describes the function block and its parameters in detail
- describes the use of the block in the S7 program

The function block is made available as a demo program. It is only intended to serve as an example to the user. Any use of this function block for machine control is at your own risk. The authors and rights holders of this code package disclaim any liability for the functionality or compatibility of this demo version.

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The function block is unencrypted. Its code can be extended and adapted to own needs.

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# Requirements

# 2. Requirements

- IFM Video Processing Unit (VPU) of the OVP81x series with PLC server application and protocol version V2.x
- Siemens S7-1500 CPU with firmware V2.6 or higher
- S7 CPU cycle time < 20ms
- Siemens TIA Portal Software V16 or higher



# 3. Function Block Description

#### Version

Version V1.0

#### Use

Simplification of the interface in the V2.x protocol of a Video Processing Unit (VPU) of the OVP81x series in the PLC user program

#### Features

- Automatically adjusts to the endianness used
- Establishing a TCP connection to the VPU PLC server
- Monitoring the connection to the PLC server
- Receiving the result data and displaying it at the outputs
- Sending commands to an ODS application in the VPU
- Sending commands to two PDS applications in the VPU

#### **Required additional program blocks**

- Siemens system function block TRCV\_C
- Siemens system function block TSEND

#### Layout







# Input parameters

Nan	ne	Data type		Description
LocIF_ID		HW_INTERFACE		Hardware identifier of the Ethernet interface used by the PLC (see chapter <u>6.4</u> )
				<ul> <li>preset with 64 and hidden if no other value or variable is assigned</li> </ul>
Lock	PortNo	Uln	t	TCP port No. of the CPU for this TCP connection
				<ul> <li>0 = the FB uses LocPortNo = 3000 + RemIPaddr4, otherwise [20005000] recommended</li> <li>preset with 0 and hidden if no other value or variable is</li> </ul>
				assigned
Rem	nIPaddr14	USI	nt	IP address of the Video Processing Unit (VPU)
Ren	nPortNo	UIn	t	TCP port No. of the PLC-server-application of the Video Processing Unit (VPU)
Con	nID	CON	NN_OUC	Unique number for internal identification of this connection
				• 0 = the FB uses <i>ConnID</i> = 3000 + <i>RemIPaddr4</i> , otherwise [14095] valid
				<ul> <li>preset with 0 and hidden if no other value or variable is assigned</li> </ul>
Con	nect	Bool		• TRUE establishes a connection to the PLC server of the VPU
				<ul> <li>FALSE terminates the connection to the PLC server of the VPU</li> </ul>
ODS	_Params	Struct		ODS parameters
	Enable		Bool	Enable ODS commands
	TimeoutTime		Time	Command response timeout time
	PresetID		USInt	Zone Preset ID to activate
	MaxHeight		UInt	Maximum height to activate
	OverhangMask		Word	Overhanging load mask to activate
PDS	_Command	Array[01] of Struct		PDS commands
	Select		USInt	Selection of the PDS command to be executed
				1 = Get Rack
				2 = Get Pallet 3 = Get Item
				4 = Volume Check
	TimeoutTime		Time	Command response timeout time
	GetRack		see <u>Table 2</u>	Get Rack command parameters



GetPallet	see <u>Table 3</u>	Get Pallet command parameters
Getltem	see <u>Table 4</u>	Get Item command parameters
VolCheck	see <u>Table 5</u>	Volume Check command parameters

# Get Rack command parameters structure

Name		Data type		Description
Get	Rack	Stru	ct	Get Rack command parameters
	HorizontalDropPosition		UInt	Selection of the horizontal drop setting 0 = left 1 = center 2 = right
	VerticalDropPosition		UInt	Selection of the vertical drop setting 0 = interior 1 = floor
	DepthHint		Int	Estimated distance between rack and coordinate system center [mm]
	ZHint		Int	Estimated z-coordinate of the rack shelf [mm]
	ClearingVolumeXMin		Int	Minimum x-coordinate [mm] of the volume which will be checked for obstacles
	ClearingVolumeXMax		Int	Maximum x-coordinate [mm] of the volume which will be checked for obstacles
	ClearingVolumeYMin		Int	Minimum y-coordinate [mm] of the volume which will be checked for obstacles
	ClearingVolumeYMax		Int	Maximum y-coordinate [mm] of the volume which will be checked for obstacles
	ClearingVolumeZMin		Int	Minimum z-coordinate [mm] of the volume which will be checked for obstacles
	ClearingVolumeZMax		Int	Maximum z-coordinate [mm] of the volume which will be checked for obstacles



# Get Pallet command parameters structure

Table 3

Name		Data type		Description	
GetPallet		Struct		Get Pallet command parameters	
	DepthHint		Int	Estimated distance between pallet and calibrated coordinate system center [mm]. <=0 for automatic detection	
	PalletIndex		Int	Index of the pallet parameter set [09]	
	PalletOrder		Int	0 = scoreDescending 1 = Descending 2 = Ascending	

## Get Item command parameters structure

Table 4

Name		Data type		Description
Getltem		Struct		Get Item command parameters
	DepthHint	-	Int	Estimated distance between pallet and calibrated coordinate system center [mm]. <=0 for automatic detection
	ItemIndex		Int	Index of the item parameter set [09]
	ItemOrder		Int	0 = scoreDescending 1 = Descending 2 = Ascending

# Volume Check command parameters structure

Name		Data type		Description
Vol	Check	Stru	ct	Volume Check command parameters
	VolumeXMin		Int	Minimum x-coordinate [mm] of the volume which will be checked for pixels
	VolumeXMax		Int	Maximum x-coordinate [mm] of the volume which will be checked for pixels
	VolumeYMin		Int	Minimum y-coordinate [mm] of the volume which will be checked for pixels
-	VolumeYMax		Int	Maximum y-coordinate [mm] of the volume which will be checked for pixels
	VolumeZMin		Int	Minimum z-coordinate [mm] of the volume which will be checked for pixels
	VolumeZMax		Int	Maximum z-coordinate [mm] of the volume which will be checked for pixels



## **Output parameters**

## Table 6

Name		Data type		Description
Connected		Вос	bl	TRUE = TCP connection established to the PLC server of the VPU
Cor	nError	Вос	bl	TRUE = Communication error occurred
Cor	nStatus	Stri	ng[12]	Communication status information (see Table 13)
OD.	S_Result	see	<u>Table 7</u>	ODS result data
PDS	5_Result	Arra Stru	ay[01] of uct	PDS result data
	CommandSuccess		Bool	TRUE = PDS Command successfully completed
	CommandFailed	-	Bool	TRUE = PDS Command failed
	CommandErrorInfo		String[12]	PDS Command error information (see Table 14)
	GetRack		see <u>Table 8</u>	Get Rack result data
	GetPallet		see <u>Table 9</u>	Get Pallet result data
	GetItem		see <u>Table 10</u>	Get Item result data
	VolCheck		see <u>Table 11</u>	Volume Check result data
DiagnosticData		Array[019] of Struct		Diagnostic data
	Source		UInt	Diagnose trigger source
	Severity		UInt	Severity
	DiagnosticID		UDInt	Diagnostic ID

# ODS result data structure

Name		Data type		Description
ODS_Result		Stru	ıct	ODS result data
	ActivatePresetSuccess		Bool	TRUE = Activate Zone Preset successfully completed
	ActivatePresetFailed		Bool	TRUE = Activate Zone Preset failed
	ActivatePresetErrorInfo	-	String[12]	Activate Zone Preset error information (see <u>Table 14</u> )
	SetMaxHeightSuccess		Bool	TRUE = Set Maximum Height successfully completed
	SetMaxHeightFailed		Bool	TRUE = Set Maximum Height failed
	SetMaxHeightErrorInfo		String[12]	Set Maximum Height error information (see <u>Table 14</u> )



Function Block Description

SetOverhangSuccess	Bool	TRUE = Set Overhanging Load Mask successfully completed
SetOverhangFailed	Bool	TRUE = Set Overhanging Load Mask failed
SetOverhangErrorInfo	String[12]	Set Overhanging Load Mask error information (see <u>Table 14</u> )
ResultAge	UInt	Result age indicator (incremented with the age of the result data, max value: 255)
Timestamp	LDT	Time stamp of ODS algorithm result
ZoneConfigID	UDInt	Current zone configuration ID
Zone1occ	Bool	TRUE = Zone 1 occupied
Zone2occ	Bool	TRUE = Zone 2 occupied
Zone3occ	Bool	TRUE = Zone 3 occupied
PolarOcc	Array[0674] of UInt	Polar occupancy grid values

# Get Rack result data structure

Nan	Name		a type	Description
Get	GetRack		ct	Get Rack result data
	ResultAge		UInt	Result age indicator (incremented with the age of the result data, max value: 255)
	Timestamp		LDT	Time stamp of PDS algorithm result
	DetectionValid		Bool	TRUE = valid results FALSE = invalid detection
	PositionX		Int	X-coordinate of the rack position [mm]
	PositionY		Int	Y-coordinate of the rack position [mm]
	PositionZ		Int	Z-coordinate of the rack position [mm]
	Roll		Int	Rotation of the rack about the x-axis [milliradians]
	Pitch		Int	Rotation of the rack about the y-axis [milliradians]
	Yaw	-	Int	Rotation of the rack about the z-axis [milliradians]
	NumPixels		UDInt	Number of pixels inside the clearing volume
	AnchoredSide		Int	0 = left 1 = center 2 = right
	Flags		Word	Bitmask encoding the detection status bits



# Get Pallet result data structure

Name		Data type		Description
Get	GetPallet		ict	Get Pallet result data
	ResultAge		UInt	Result age indicator (incremented with the age of the result data, max value: 255)
	Timestamp		LDT	Time stamp of PDS algorithm result
	DetectionValid		Bool	TRUE = valid results FALSE = invalid detection
	PalletIndex		Int	Index of the parameter set which was used to detect the pallet
	CenterX		Int	X-coordinate of the center block [mm]
	CenterY		Int	Y-coordinate of the center block [mm]
	CenterZ		Int	Z-coordinate of the center block [mm]
	LeftPocketX		Int	X-coordinate of the left pocket [mm]
	LeftPocketY		Int	Y-coordinate of the left pocket [mm]
	LeftPocketZ		Int	Z-coordinate of the left pocket [mm]
	RightPocketX		Int	X-coordinate of the right pocket [mm]
	RightPocketY		Int	Y-coordinate of the right pocket [mm]
	RightPocketZ		Int	Z-coordinate of the right pocket [mm]
	Roll		Int	Pallet's rotation about the x-axis [milliradians]
	Pitch		Int	Pallet's rotation about the y-axis [milliradians]
	Yaw		Int	Pallet's rotation about the z-axis [milliradians]



# Get Item result data structure

#### Table 10

Name		Data type		Description
GetItem		Struct		Get Item result data
	ResultAge		UInt	Result age indicator (incremented with the age of the result data, max value: 255)
	Timestamp		LDT	Time stamp of PDS algorithm result
	Score		UInt	Detection score. 0 = invalid detection
	ItemIndex		Int	ID of the fitted item
	PositionX		Int	X-coordinate of the item's principal point [mm]
	PositionY		Int	Y-coordinate of the item's principal point [mm]
	PositionZ		Int	Z-coordinate of the item's principal point [mm]
	Roll		Int	Item's rotation about the x-axis [milliradians]
	Pitch		Int	Item's rotation about the y-axis [milliradians]
	Yaw		Int	Item's rotation about the z-axis [milliradians]

# Volume Check result data structure

Name		Data type		Description
VolCheck		Struct		Volume Check result data
	ResultAge		UInt	Result age indicator (incremented with the age of the result data, max value: 255)
	Timestamp		LDT	Time stamp of PDS algorithm result
	NumPixels		UDInt	Number of pixels inside the volume
	NearestX		DInt	Smallest x-coordinate inside the volume (derived from quantile) [mm]



# 4. Integration of the Function Block into the User Program

# 4.1. Inserting the Function Block into the User Program

The function block *OVP81x-ProtV2* uses the blocks *TRCV\_C* version V3.2 and *TSEND* version V4.0 from the integrated Open user communication library V7.0 (see Figure 2).

If you use other versions of these Siemens blocks in your project, this can lead to errors in the translation of the function block *OVP81x-ProtV2*. To avoid this, set your project to the version of the *Open user communication* library V7.0 before inserting the function block, or use a library version that includes the above versions of TRCV\_C and TSEND. Note: The *Instructions* tab is visible only when you open any code block of your program.

Alternatively, you can edit the *OVP81x-ProtV2* function block after insertion and update the declarations and calls of the TRCV\_C and TSEND blocks. Please note that other versions of these blocks may behave differently.

In	structions		- □ >	
0	Options			
	the tee	<del>5</del> 5		Inst
>	Favorites			ruct
>	> Basic instructions			
>	Extended instructions			
>	Technology			
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Name		Description	Version	tin
•	57 communication		V1.3	9
•	Dpen user communication		<u>V7.0</u>	
	TSEND_C	Establishing	V3.2	-
	TRCV_C	Establishing	V3.2	as
	TMAIL_C	Send e-mail	V6.0	ks
	🔻 🛅 Others			
	TCON	Establish co	V4.0	
	TDISCON	Terminate co	V2.1	Lib
	TSEND	Send data via	V4.0	rar
		Receive data	V4.0	ē
Figı	ure 2			

- > Copy the function block *OVP81x-ProtV2* into your TIA Portal project.
- Compile the function block.
- Create an instance of the OVP81x-ProtV2 function block. If you want to use several Video Processing Units, create a separate instance of the function block for each VPU in the user program.

# 4.2. Setting the Connection Parameters

The PLC and the Video Processing Unit (VPU) can only communicate on the network if they are on the same subnet. The most used subnet mask is 255.255.255.0. This means that the first three parts of the IP address must be the same for all devices on this subnet, and the last part must be different and unique in each device.

- Set the IP address and subnet mask in the Video Processing Unit. There are various ways to do this, for example with the help of the VisionAssistant software, which you can download from <u>www.ifm.com</u>.
- Set the IP address and subnet mask of the Ethernet interface of the S7 CPU (see chapter <u>6.3</u>).



The TCP connection between PLC and VPU is only created and set up in the PLC user program. Do not configure this connection in the Devices & networks section of the TIA Portal project.

Define the endpoints of the TCP connection between PLC and the PLC server application of the VPU. To do this, assign fixed values to the following connection parameters for each instance of the function block. Make sure that multiple instances are not communicating with the same VPU.

## LocIF\_ID

Enter the hardware identifier of the Ethernet interface used by the PLC (see chapter <u>6.4</u>).

This parameter of the function block is preset with the value 64. This corresponds to the hardware identifier of the first Ethernet interface of most standard CPUs. The parameter is hidden if the default assignment is not changed. If you are using a different CPU or interface, expand the block parameters display and change the assignment according to your hardware.



## LocPortNo

Specify the TCP port number that the PLC should use internally to connect to the VPU.

This parameter of the function block is preset with the value 0. With this setting, the function block calculates the locally used port number from 3000 + the value of the input parameter *RemlPaddr4*. However, the device cannot check whether the calculated local port number is still free. The parameter is hidden if the default assignment is not changed. If you want to set the local port yourself, expand the block parameters display and change the assignment according to your choice. For classic CPUs, Siemens has released the local port numbers 2000 to 5000 for use by the user. Specify a port number that has not yet been used.

Tip: If you are using a classic CPU, set *LocPortNo* = 0 on all instances of the function block *OVP81x-ProtV2*.

#### RemIPaddr1 .. RemIPaddr4

Specify the IP address of the VPU.

#### RemPortNo

> Specify the TCP port number of the PLC server application of the VPU.

#### ConnID

Assign a unique identification number to the connection. This is used in the S7 station as an internal reference. Keep in mind that connections to other devices can also occupy an ID.

This parameter of the function block is preset with the value 0. With this setting, the function block calculates the identification number from 3000 + the value of the input parameter *RemlPaddr4*. However, the block cannot check whether the calculated identification number is still free. The parameter is hidden if the default assignment is not changed. If you want to set the identification number yourself, expand the block parameters display and assign the parameter a unique value from the range between 1 and 4095.

Tip: Set *ConnID* = 0 on all instances of the function block *OVP81x-ProtV2*.

# 4.3. Calling the Instances of the Function Block in the User Program

> Call all instances of the function block OVP81x-ProtV2 in the cyclic program once per PLC cycle.



# 5. Control of the ODS and PDS Applications of the VPU with the help of the Function Block *OVP81x-ProtV2*

# 5.1. Connect to the VPU

The function block automatically adjusts to the endianness used.

## Establishing the connection

Set the signal at input parameter *Connect* = TRUE.

## The function block

- establishes a TCP connection with the set connection parameters
- shows output *Connected* = TRUE if the connection is established
- shows output *ComErrorr* = TRUE if a communication error occurred
- displays communication status information in the ComStatus output (see Table 13)
- automatically tries to reconnect in case of connection errors
- receives the data sent by the VPU and displays the individual values in the outputs

## Terminating the connection

Set the signal at input parameter *Connect* = FALSE.

The function block

- terminates the TCP connection
- displays Connected = FALSE, ComError = FALSE and ComStatus = NO\_COM

# 5.2. ODS Application Commands

The function block supports following commands for one ODS application:

- Select Zone Preset ID
- Set Maximum Height
- Set Overhanging Load Mask

Only if *Enable* = TRUE in the *ODS\_Params* inputs structure the function block sends ODS commands to the VPU.

For each of the ODS commands, the function block provides input parameters for the setting values in the ODS\_Params inputs structure.

After establishing the connection to the VPU, the function block automatically sends the setting values to the VPU. The function block then monitors the setting values. If a value changes, the function block sends the corresponding command with the new setting value to the VPU.

If the command was not executed successfully, the function block repeats the command with the current setting value until the VPU confirms the successful execution of the command.

For each of the ODS commands, the function block displays the result of the command execution in the ODS\_Result outputs structure. In addition, the function block displays the cyclic ODS data received from the VPU.

## Activating a Zone Preset in the ODS Application

The zone presets are stored in the ODS application of the VPU and identified by an ID.

- Set ODS\_Params.Enable = TRUE.
- > At the input parameter *ODS\_Params.TimeoutTime*, set the command response timeout time.
- > At the input parameter *ODS\_Params.PresetID*, set the ID of the zone preset you want to activate.

The function block

• sends the command to activate the specified zone preset every time the given ID is changed

Control of the ODS and PDS Applications of the VPU with the help of the Function Block OVP81x-ProtV2



- sends the command automatically after connecting to the VPU
- aborts the response reception every time the device does not respond within the set timeout time
- repeats sending the command periodically if it has previously failed
- displays ActivatePresetSuccess = TRUE in the output if the command was successfully executed
- shows ActivatePresetFailed = TRUE in the output if the command was not executed successfully
- displays in the ActivatePresetErrorInfo output which error occurred (see Table 14)



A positive acknowledgement of the command does not mean that the zone preset is already active in the ODS. The configuration used to determine zone occupancy is always displayed in the ODS\_Result.ZoneConfigID output.

## Setting the Maximum Height in the ODS Application

- Set ODS\_Params.Enable = TRUE.
- > At the input parameter ODS\_Params.TimeoutTime, set the command response timeout time.
- > At the input parameter ODS\_Params.MaxHeight, set the height value you want to set in the ODS application.

The function block

- sends the command to activate the specified maximum height every time the given height value is changed
- sends the command automatically after connecting to the VPU
- aborts the response reception every time the device does not respond within the set timeout time
- repeats sending the command periodically if it has previously failed
- displays SetMaxHeightSuccess = TRUE in the output if the command was successfully executed
- shows SetMaxHeightFailed = TRUE in the output if the command was not executed successfully
- displays in the SetMaxHeightErrorInfo output which error occurred (see Table 14)

#### Setting the Overhanging Load Mask in the ODS Application

- Set ODS\_Params.Enable = TRUE.
- > At the input parameter *ODS\_Params.TimeoutTime*, set the command response timeout time.
- > At the input parameter ODS\_Params.OverhangMask, set the bit mask you want to set in the ODS application.

The function block

- sends the command to activate the specified bit mask every time the given bit mask is changed
- sends the command automatically after connecting to the VPU
- aborts the response reception every time the device does not respond within the set timeout time
- repeats sending the command periodically if it has previously failed
- displays SetOverhangSuccess = TRUE in the output if the command was successfully executed
- shows SetOverhangFailed = TRUE in the output if the command was not executed successfully
- displays in the SetOverhangErrorInfo output which error occurred (see <u>Table 14</u>)

## 5.3. PDS Application Commands

The function block supports two individual PDS applications.

For each of the PDS applications, the function block provides a separate entry for the input parameters in the *PDS\_Command[]* array. The function block also displays the result data of each of the PDS applications in a separate entry in the *PDS\_Result[]* output array.

The function block supports the commands listed in <u>Table 12</u> for each PDS application. You can select a command using the <u>Select</u> input parameter in the <u>PDS\_Command[]</u> structure.



Table 12

Select	Command			
1	Get Rack			
2	Get Pallet			
3	Get Item			
4	Volume Check			
Other	No command			

For each of the PDS commands, the function block provides individual substructures with input parameters for the specific setting values in the PDS Command[] inputs structure.

After establishing the connection to the VPU, the function block automatically sends the selected PDS command of each PDS application with the actual setting values to the VPU. The function block then monitors the setting values as long the command is selected. If one of the values changes or a different command is selected, the function block sends the corresponding command with the new setting values to the VPU.

If the command was not executed successfully, the function block repeats the command with the current setting values until the VPU confirms the successful execution of the command or the command is deselected.

The function block displays in the PDS\_Result[] output structure whether the command was executed successfully. The command result is displayed as long the command is selected. The command success is displayed only if the VPU sends the requested data. The function block displays this data for each command in a separate substructure. If another command is activated, the last received data of this command remains displayed.

## **Executing a PDS Command**

- In the specific input parameter structure PDS\_Command[].<command>, set the values of the command parameters.
- At the input parameter PDS Command[]. Timeout Time, set the command response timeout time.  $\geq$
- Set the input parameter PDS\_Command[].Select to the specific value of the command (see Table 12).  $\triangleright$

The function block sends the selected command to the specific PDS application of the VPU.

As long the command is still selected, the function block

- sends the command with current setting values if one of the setting values is changed •
- aborts the response reception every time the device does not respond within the set timeout time .
- repeats sending the command periodically with current setting values if it has previously failed
- displays PDS Result[].CommandSuccess = TRUE if the command was successfully executed and the VPU sends the requested data
- shows PDS\_Result[].CommandFailed = TRUE if the command was not executed successfully
- displays in the PDS Result[].CommandErrorInfo output which error occurred (see Table 14)
- displays the command result data of the VPU in the PDS\_Result[].<command> substructure



# 6. Appendix

# 6.1. Display in the Output Parameter ComStatus

ComStatus	Description				
NO_ERROR	No error				
NO_COM	No communication with the PLC server of the VPU				
CONNECTING	Establishing connection to the PLC server of the VPU				
DEVICE_PROT	Device communication frame protocol error				
PROT_VERSION	Wrong protocol version of the PLC server application of the VPU				
TIMEOUT	Timeout of receiving cyclic data from VPU				
TRCV_C	Siemens system function block TRCV_C displays an error. The reported error code follows as hexadecimal value. The complete list of error codes of the block can be found in the Siemens documentation of the block. Here is an excerpt of the most common error codes:				
8085 8086 8087 8091 809B	Parameter LEN or DATA changed after first call or out of range Parameter <i>ConnID</i> out of range Maximum number of connections reached, no additional connection possible Maximum nesting depth exceeded Parameter <i>HW_ID</i> does not point to the CPU Ethernet-interface				
80A1	<ul> <li>Connection or port already being used by the user</li> <li>The specified connection has not yet been established</li> <li>The specified connection is being terminated</li> <li>The interface is being re-initialized</li> </ul>				
80A4 80AA	IP-address at parameter <i>RemIPAddr</i> invalid or match the local IP-address A connection is currently being established with the same <i>ConnID</i> by another block				
80C3	<ul> <li>All connection resources are in use</li> <li>A block with this <i>ConnID</i> is already processed in a different priority group</li> </ul>				
80C4	<ul> <li>The connection cannot be established at this time</li> <li>The connection is being established</li> </ul>				
80C5 80C6 80C7	Connection terminated by the communication partner The remote partner cannot be reached (network error) Execution timeout				
8922 8932	Parameter Data invalid target area, the area does not exist in the DB Parameter Data DB number is too high				
8A3A	Parameter Data no access to the data area (e.g. DB does not exist)				



# 6.2. Display in the Command Error Info Outputs in ODS\_Result and PDS\_Result Structures

Tab		1 /
Tab	ie.	14

ErrorInfo	Description
NO_ERROR	No error
NO_SELECTION	No command selected
NO_COM	No communication with the PLC server of the VPU
TIMEOUT	Timeout of receiving command response
INVALID_CMD	Unknown command
NOT_POSSIBLE	Device unable to execute the command due to parameter range or device state
RESPONSE_LEN	Unexpected response length received. Data cannot be evaluated.

# 6.3. Setting the IP Address of the CPU in the TIA Portal

- Open the device configuration of the S7 station
- Switch to the Device view and select the CPU.
- By double-clicking on the Ethernet interface of the CPU used, you open the properties of the Ethernet interface.
- Open the General tab.
- In the Ethernet addresses folder, set the IP address and the subnet mask.



## 6.4. Displaying the Hardware ID of the CPU Ethernet Interface in the TIA Portal

- Open the properties of the Ethernet interface as described in Chapter <u>6.3</u>
- **Properties** 🗓 Info 追 🗓 Diagnostics 📃 🗉 General IO tags System constants Texts Hardware identi. Used by Name Comment Туре Local~PROFINET\_interface\_1~Port\_1 Hw\_Interface 65 PLC\_1 Hw\_Interface Local~PROFINET\_interface\_1~Port\_2 66 PLC\_1 Local~PROFINET\_interface\_1 Hw\_Interface 64 PLC\_1
- Open the System constants tab.

Figure 4

The hardware identifier of the Ethernet interface is displayed here. Specify this identifier at the instance of the function block *OVP81x-ProtV2* at the input parameter *LocIF\_ID*.